

Free boundary equilibrium codes

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1 Free boundary equilibrium problem

2 Research work

- Complex poloidal circuits
- Average quantities over closed flux loop

Grad-Schafranov equation

- Ideal MHD equilibrium satisfies balance

Ideal MHD

$$\nabla p = j \times B \quad (1)$$

- Two-dimensional nonlinear partial differential equation about ψ .

Grad-Schafranov equation

$$\Delta^* \psi + \mu_0 R^2 \frac{\partial}{\partial \psi} p(R, \psi) + g \frac{\partial g}{\partial \psi} = 0 \quad (2)$$

Free boundary problem

- ψ at any point of computational box via equation

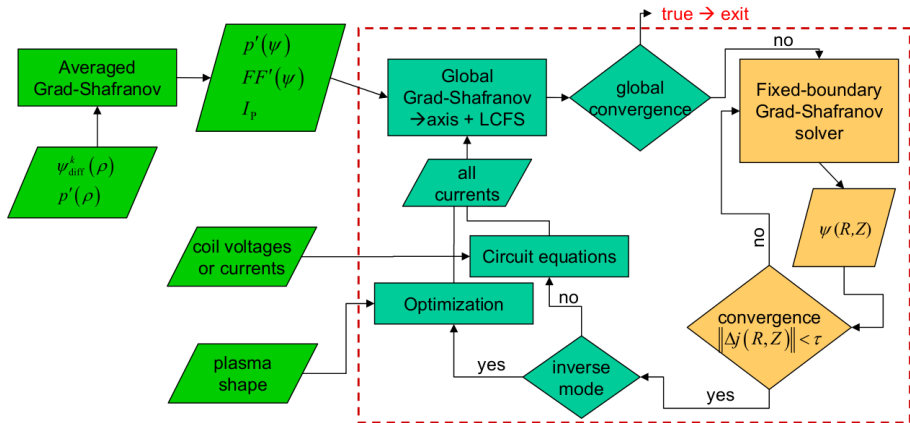
$$\psi(R', Z') = \int_P G(R, Z; R', Z') J_\phi dR dZ + \sum_{i=1}^{N_c} G(R_i^c, Z_i^c; R', Z') I_\phi$$

- J_ϕ may be obtained from ψ

$$J_\phi = -\frac{1}{\mu_0 R} \Delta^* \psi$$

- ψ is result of G-S equation (2)
- In order to solve G-S eq., boundary conditions ψ_b are necessary \Rightarrow
Initial guess of ψ_b

FREEBIE scheme



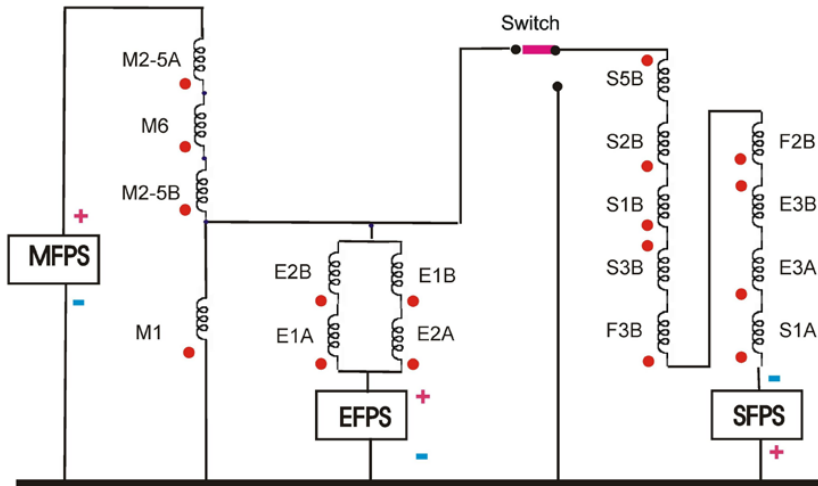
Flow chart of FREEBIE code, [Urban, 2012]

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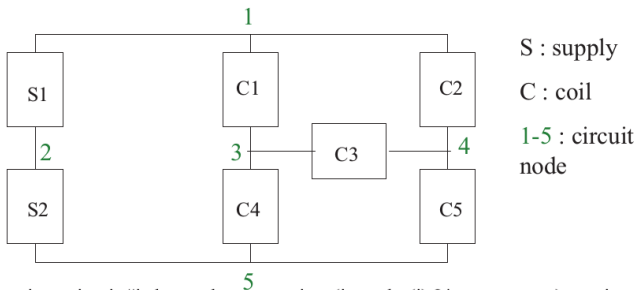
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Motivation



PF coils power supply circuits, [Havlicek,2011]

Circuit matrix



For the given circuit #i above, the connections(i,nnodes(i),2*ncomponent) matrix reads:

	S1(1)	S1(2)	S2(1)	S2(2)	C1(1)	C1(2)	C2(1)	C2(2)	C3(1)	C3(2)	C4(1)	C4(2)	C5(1)	C5(2)
1	[1	0	0	0	1	0	1	0	0	0	0	0	0	0]
2	[0	1	1	0	0	0	0	0	0	0	0	0	0	0]
3	[0	0	0	0	0	1	0	0	1	0	1	0	0	0]
4	[0	0	0	0	0	0	0	1	0	1	0	0	1	0]
5	[0	0	0	1	0	0	0	0	0	0	0	1	0	1]]

Matrix describing general circuit

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Equipotential

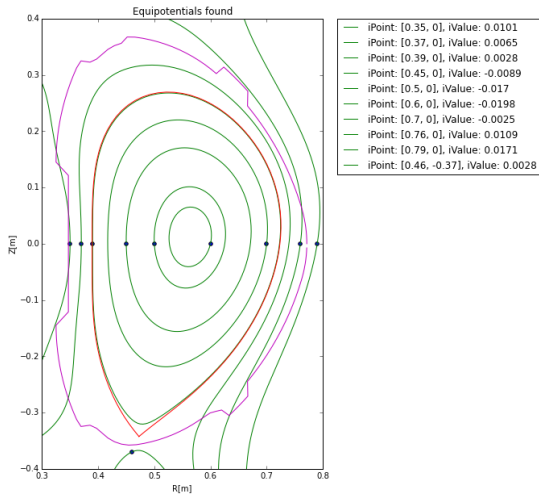
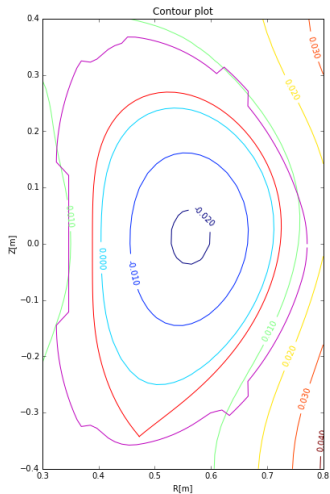
- Additional dependency $x(\lambda), y(\lambda)$

$$\begin{aligned} F(x, y) &= 0, \\ \frac{\partial F}{\partial x} \frac{dx}{d\lambda} + \frac{\partial F}{\partial y} \frac{dy}{d\lambda} &= 0, \\ (d\lambda)^2 &= (dx)^2 + (dy)^2, \end{aligned}$$

- results in set of differential equations

$$\begin{aligned} \frac{dx}{d\lambda} &= \mp \frac{F_y}{\sqrt{F_x^2 + F_y^2}}, \quad x(0) = x_0, \\ \frac{dy}{d\lambda} &= \pm \frac{F_x}{\sqrt{F_x^2 + F_y^2}}, \quad y(0) = y_0. \end{aligned}$$

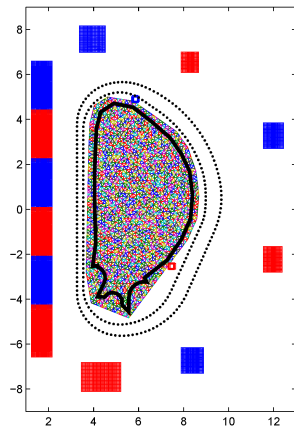
My own contour plot








Comparison of contour plot and algorithm results

Problem and possible solution

- Data grid
- SmoothBivariateSpline class smoothing factor
- My own spline class



Triangulation grid used by FREEBIE code, [Urban, 2012]

-  Kuznetsov, E.B. *Optimal parametrization in numerical construction of curve*. Journal of the Franklin Institute, 2007. 344(5): p. 658-671
-  KRBALEK, Milan. *Úlohy matematické fyziky*. Prague: Czech technical university, 2012. ISBN 978-80-01-05000-2.
-  JARDIN, Stephen. *Computational methods in plasma physics*. Boca Raton, FL: CRC Press/Taylor, 2010. ISBN 978-143-9810-958.
-  HAVLICEK, J., R. BEŇO a J. STÖCKEL. *A Simulation of the COMPASS Equilibrium Field Power Supply PID Controller*. Prague: Matfyzpress, 2011, s. 221-226. ISBN 978-80-7378-185-9.
-  URBAN, J. and J.-F. ARTAUD. *Coupled transport and free-boundary equilibrium simulations using FREEBIE and CRONOS*. 2012.

The End

Definition

- $LG(x, s) = \delta(x - s)$

Motivation

- $Lu(x) = f(x)$
- $\int LG(x, s)f(s)ds = \int \delta(x - s)f(s)ds = f(x)$
- $u(x) = \int G(x, s)f(s)ds$